A *-product approach to non-autonomous linear ordinary differential equations

Stefano Pozza, Niel Van Buggenhout

Charles university, Prague

Jablonec nad Nisou - PANM 2022 June 19–24, 2022

Our teams Local team (Charles University)









- S. Pozza (PI)
- N. Van Buggenhout (Posdoc)
- S. Zahid (Ph.D.)

M. Faisal (Ph.D.)

External team



C. Bonhomme (Sorbonne-Univ.)



P-L. Giscard (ULCO)



M. Redivo-Zaglia (Padova-Univ.)



S. Cipolla (Edinburgh-Univ).

Nuclear Magnetic Resonance (NMR) spectroscopy analyses dynamics of nuclear spins in magnetic field:

$$\hbar \frac{d}{dt} \Psi(t) = -iH(t)\Psi(t),$$

with

wave function $\Psi(t)$ Hamiltonian H(t)

- ℓ spins \rightarrow size $2^\ell \times 2^\ell$
- Sparse

Nuclear Magnetic Resonance (NMR) spectroscopy analyses dynamics of nuclear spins in magnetic field:

$$\hbar \, \frac{d}{dt} \Psi(t) = -i H(t) \Psi(t)$$

with

wave function $\Psi(t)$

Hamiltonian H(t)

- ℓ spins \rightarrow size $2^\ell \times 2^\ell$
- Sparse

4 strongly coupled spins

Nuclear Magnetic Resonance (NMR) spectroscopy analyses dynamics of nuclear spins in magnetic field:

$$\hbar \, \frac{d}{dt} \Psi(t) = -i H(t) \Psi(t),$$

with

wave function $\Psi(t)$

Hamiltonian H(t)

- ℓ spins \rightarrow size $2^\ell \times 2^\ell$
- Sparse

4 uncoupled spins + pulse wave



Nuclear Magnetic Resonance (NMR) spectroscopy analyses dynamics of nuclear spins in magnetic field:

$$\hbar \, \frac{d}{dt} \Psi(t) = -i H(t) \Psi(t)$$

with

wave function $\Psi(t)$ Hamiltonian H(t)

- $\ell \text{ spins} \to \text{size } 2^{\ell} \times 2^{\ell}$
- Sparse

Why? Computer simulation improves design improves analysis of practical experiments

4 uncoupled spins + pulse wave



Numerical methods - references (incomplete list)

- o [Moro, Freed, 1981]
- [Tal-Ezer, Kosloff, 1984]
- o [Park, Light, 1985]
- [Leforestier et al., 1991]
- o [Chin, Chen, 2002]
- o [Hochbruck, Lubich, 2003]
- [Veshtort, Griffin, 2006]
- [Lauvergnat, Blasco, Chapuisat, 2007]
- [Kormann, Holmgren, Karlsson, 2008]
- o [Lubich, 2008]

Softwares: SIMPSON, SPINACH.

o [Blanes, Casas, Oteo, Ros, 2009]

- [Tošner, Vosegaard, Kehlet, Khaneja, Glaser, Nielsen, 2009]
- o [Mazzi, 2010]
- [Sánchez, Casas, Fernández, 2011]
- [Iserles, Munthe-Kaas, Nørsett, Zanna, 2015]
- o [Blanes, Casas, Murua, 2015]
- [Bader, Iserles, Kropielnicka, Singh, 2016]
- o [Blanes, Casas, 2016]

o ...

Outline

- ► Solution of ODEs by *-product.
- From the *-product algebra to the matrix algebra.
- ► A new NLA approach for linear ODEs.

Scalar ODE

For the sake of a simpler explanation, consider the scalar problem:

$$\frac{d}{dt}u(t) = \tilde{f}(t)u(t), \quad u(s) = 1, \quad t \ge s \in I \subset \mathbb{R}$$

with $\tilde{f}(t)$ a smooth and bounded function over I. Then

$$u(t) = \exp\left(\int_{s}^{t} \tilde{f}(\tau) \,\mathrm{d}\tau\right).$$

We are going to show an alternative expression for the solution. Everything we are going to see can be easily extended to a system of ODEs.

Volterra composition

Let $\tilde{f}_1(t,s), \tilde{f}_2(t,s)$ be bivariate matrices. The following operation

$$\left(\tilde{f}_2 \star_v \tilde{f}_1\right)(t,s) := \int_s^t \tilde{f}_2(t,\tau) \tilde{f}_1(\tau,s) \,\mathrm{d}\tau.$$

is known as Volterra composition. Picard iteration:

$$\begin{split} \frac{d}{dt'}u(t) &= \tilde{f}(t)u(t), \quad u(s) = 1 \\ &\downarrow \text{ integration} \\ u(t) &= 1 + \int_s^t \tilde{f}(\tau)u(\tau)\mathrm{d}\tau \\ &\downarrow \text{ integration} \\ u(t) &= 1 + \int_s^t \tilde{f}(\tau) \left(1 + \int_s^\tau \tilde{f}(\rho)u(\rho)\mathrm{d}\rho\right)\mathrm{d}\tau \\ &= 1 + \int_s^t \tilde{f}(\tau) + \int_s^\tau \tilde{f}(\tau)\tilde{f}(\rho)u(\rho)\mathrm{d}\rho\mathrm{d}\tau \\ &\downarrow \text{ after many iterations} \\ u(t) &= 1 + \int_s^t \tilde{f}(\tau)\mathrm{d}\tau + \int_s^t \tilde{f}^{\star_v 2}(\tau)\mathrm{d}\tau + \dots = 1 + \int_s^t \sum_{j=1}^\infty \tilde{f}^{\star_v j}(\tau)\mathrm{d}\tau. \end{split}$$

*-product

We extend the Volterra composition defining the so-called ***-product**

$$(f_2 \star f_1)(t,s) := \int_{-\infty}^{+\infty} f_2(t,\tau) f_1(\tau,s) \,\mathrm{d}\tau.$$

that is an actual product for a specific class of distributions [Giscard, P., Ryckebusch].

Let $\Theta(t-s)$ be the Heaviside function

$$\Theta(t-s) = \begin{cases} 1, t \ge s, \\ 0, t < s \end{cases}$$

Then

$$\tilde{f}_2(t-s)\Theta(t-s)\star\tilde{f}_1(t,s)\Theta(t-s)=\tilde{f}_2(t,s)\star_v\tilde{f}_1(t,s).$$

S.Pozza, N. Van Buggenhout

Definition: *-product

- $f_1(t,s)$, $f_2(t,s)\in$ specific class of distributions
- $(f_2 \star f_1)(t,s) := \int_{-1}^1 f_2(t,\tau) f_1(\tau,s) d\tau$

Definition: \star -product

- $f_1(t,s)$, $f_2(t,s)\in$ specific class of distributions
- $(f_2 \star f_1)(t,s) := \int_{-1}^1 f_2(t,\tau) f_1(\tau,s) d\tau$

The class consists of $f(t,s) = \tilde{f}(t)\Theta(t-s)$

- $\tilde{f}(t)$ smooth

- Heaviside function
$$\Theta(t-s) = \begin{cases} 1, & t \ge s \\ 0, & t < s \end{cases}$$

Definition: \star -product

- $f_1(t,s)$, $f_2(t,s)\in$ specific class of distributions
- $(f_2 \star f_1)(t,s) := \int_{-1}^1 f_2(t,\tau) f_1(\tau,s) d\tau$

The class consists of $f(t,s) = \tilde{f}(t)\Theta(t-s)$

- $\tilde{f}(t)$ smooth

- Heaviside function
$$\Theta(t-s) = \begin{cases} 1, & t \ge s \\ 0, & t < s \end{cases}$$

Example: $\tilde{f}(t) = \cos(4t)$ $f(t,s) = \cos(4t)\Theta(t)$



0.5



Definition: \star -product

- $f_1(t,s)$, $f_2(t,s)\in$ specific class of distributions
- $(f_2 \star f_1)(t,s) := \int_{-1}^1 f_2(t,\tau) f_1(\tau,s) d\tau$

The class consists of $f(t,s) = \tilde{f}(t)\Theta(t-s)$

- $\tilde{f}(t)$ smooth

- Heaviside function
$$\Theta(t-s) = \begin{cases} 1, & t \ge s \\ 0, & t < s \end{cases}$$

Example: $\tilde{f}(t) = \cos(4t)$ $f(t,s) = \cos(4t)\Theta(t-s)|_{s=0}$



The *-product algebra

$$r(t,s) = f(t,s) \star g(t,s)$$

$$f + g$$

$$1_{\star} = \delta(t-s)$$

$$f^{\star-1}(t,s)$$

$$R_{\star}(f)(t,s) := (1_{\star} - f)^{\star-1}(t,s)$$

 $\tilde{f} \Theta \star \tilde{g} \Theta \to \tilde{r} \Theta$, closed closed Dirac delta Dirac delta derivatives δ', δ'', \dots \star -resolvent

Solution by *-resolvent

Let us define $f(t,s) = \tilde{f}(t)\Theta(t-s)$. The *-resolvent is defined as

$$\mathsf{R}_{\star}(f) := (1_{\star} - f)^{\star - 1} = 1_{\star} + \sum_{k \ge 1} f^{\star k}$$

with $1_{\star} = \delta(t - s)$ the Dirac delta function. The \star -resolvent exists if f is bounded for $t, s \in I$. Then the Time-ordered exponential can be given as

$$\mathsf{U}(t,s) = \int_{s}^{t} \mathsf{R}_{\star}(f)(\tau,s) \, d\tau = \Theta(t-s) \star \mathsf{R}_{\star}(f)(t,s)$$

where for a fixed s, U(t,s) solves the ODE with starting time s; [Giscard & al., 2015].

Example

Consider the simple case $\widetilde{f}(t) = 1$,

$$\frac{d}{dt}u(t) = u(t), \quad u(s) = 1.$$

Then $f(t,s) = \Theta(t-s)$ and

$$R_{\star}(f)(t,s) = \sum_{k=0}^{\infty} \Theta(t-s)^{\star k}.$$

Hence

$$U(t,s) = \Theta(t-s) \star R_{\star}(f)(t,s) = \sum_{k=0}^{\infty} (\Theta(t-s))^{*(k+1)} = \sum_{k=0}^{\infty} \frac{(t-s)^k}{(k)!} \Theta(t-s).$$

As expected, for a fixed s, the solution is

$$u(t) = U(t,s) = \exp(t-s)\Theta(t-s).$$

S.Pozza, N. Van Buggenhout

Vito Volterra

§ 4. - Risoluzione generale di equazioni integrali. 9. Abbiasi una funzione analitica del tipo (1) $F(z_1, z_2, ..., z_n).$ Scriviamo l'equazione (4) $\mathbf{F}(z_1, z_2, \dots, z_n) = 0.$ $S(x, y) = R(x, y) - \frac{1}{2} R^{2}(x, y) + \frac{1}{2} R^{3}(x, y) - \dots + \frac{(-1)^{n}}{n} R^{n}(x, y) + \dots$ ove $\mathbf{R}^{n}(x, y) = \int^{y} \mathbf{R}^{n-1}(x, \xi) \, \mathbf{R}(\xi, y) \, d\xi \, .$ e non dovremo porre alcuna limitazione per i valori assoluti di S(x, y), R(x, y), purchè siano finiti. 10 Supponiamo in particolare che la (4') sia un polinomio razionale e

[Volterra, Rend Lincei, 1910]

Vito Volterra - 91 years from "fascism oath" rejection

- In 1931, the Italian fascist regime imposed an oath of allegiance to the fascist government to all university professors.
- Only 12 professors refused to sign it. They lost their position.
- Vito Volterra was one of them. He was marginalized from the Italian scientific community (from '38, also because of the racial laws).
- First helped by the Vatican Science Academy, he then lived in Spain and France.



Systems of ODEs

Let $t \ge s \in I \subseteq \mathbb{R}$, A(t) a time dependent matrix. The time-ordered exponential is the unique solution U(t, s) of

$$\widetilde{\mathsf{A}}(t)\mathsf{U}(t,s) = \frac{d}{dt}\mathsf{U}(t,s), \quad \mathsf{U}(s,s) = \mathsf{I}_N.$$

If $\widetilde{\mathsf{A}}(\tau_1)\widetilde{\mathsf{A}}(\tau_2) = \widetilde{\mathsf{A}}(\tau_2)\widetilde{\mathsf{A}}(\tau_1)$ for all $\tau_1, \tau_2 \in I$, then

$$\mathsf{U}(t,s) = \exp\left(\int_s^t \widetilde{\mathsf{A}}(\tau) \, d\tau\right).$$

U has generally no explicit form. Expression by ([Dyson, 1948])

$$\mathsf{U}(t,s) = \mathcal{T} \exp\left(\int_{s}^{t} \widetilde{\mathsf{A}}(\tau) \, d\tau\right).$$

with \mathcal{T} the time-ordering operator.

S.Pozza, N. Van Buggenhout

Time-ordered exponential

The time-ordering expression is more a notation as the action of the time-ordering operator is very difficult to evaluate.

- Classical approaches Perturbative methods (Floquet-based and Magnus series techniques), often prohibitively involved, e.g., [Blanes & al., 2009];
- Path-sum approach: The expression has a finite number of scalar integro-differential equations, but its complexity can be too large; [Giscard & al., 2015].
- *-Lanczos + Path-sum: [Giscard, P., 2020-2022]

Solution by *-product

Nevertheless, the \star -resolvent expression for the solution remains:

$$U(t,s) = \Theta(t-s) \star R_{\star}(A),$$

with

$$R_{\star}(A)(t,s) = \sum_{k=0}^{\infty} \left(\widetilde{A}(t)\Theta(t-s) \right)^{\star k},$$

where the \star -product here is extended in the matrix-product sense.

The probelm is: How do we compute $R_{\star}(A)$?

Symbolic expression: Path-sum method [Giscard & al., 2015] and **-**Lanczos symbolic method [Giscard, P., 2020-2022].

Compute u(t, s)

Compute u(t,s)

- Symbolically: slow
- Numerically: rest of the presentation

Numerical procedure:

- 1. Discretize f(t,s)
- 2. Discrete analogue of *-operations
- 3. Compute discretized resolvent
- 4. Express u(t,s) in terms of resolvent

Function of interest

$$f(t,s) = \tilde{f}(t)\Theta(t-s)$$

Use Legendre polynomials $\{p_k\}$

$$\int_{-1}^{1} p_k(\tau) p_l(\tau) d\tau = \begin{cases} 0, & \text{if } k \neq l \\ 1, & \text{if } k = l \end{cases}$$

Legendre series

$$f(t,s) \approx \sum_{i=0}^{\infty} \sum_{j=0}^{\infty} f_{i,j} p_i(t) p_j(s)$$

Function of interest

$$f(t,s) = \tilde{f}(t)\Theta(t-s)$$

Use Legendre polynomials $\{p_k\}_{k=0}^{M}$

$$\int_{-1}^{1} p_k(\tau) p_l(\tau) d\tau = \begin{cases} 0, & \text{if } k \neq l \\ 1, & \text{if } k = l \end{cases}$$

Legendre series

$$f(t,s) \approx \sum_{i=0}^{M} \sum_{j=0}^{M} f_{i,j} p_i(t) p_j(s) =: f_M(t,s)$$

Function of interest

$$f(t,s) = \tilde{f}(t)\Theta(t-s)$$

Use Legendre polynomials $\{p_k\}_{k=0}^{M}$

$$\int_{-1}^{1} p_k(\tau) p_l(\tau) d\tau = \begin{cases} 0, & \text{if } k \neq l \\ 1, & \text{if } k = l \end{cases}$$

Legendre series

$$f(t,s) \approx \sum_{i=0}^{M} \sum_{j=0}^{M} f_{i,j} p_i(t) p_j(s) =: f_M(t,s)$$

$$f_M(t,s) = \begin{bmatrix} p_0(t) & p_1(t) & \dots & p_M(t) \end{bmatrix} \begin{bmatrix} f_{0,0} & f_{0,1} & \dots & f_{0,M} \\ f_{1,0} & f_{1,1} & \dots & f_{1,M} \\ \vdots & \vdots & & \vdots \\ f_{M,0} & f_{M,1} & \dots & f_{M,M} \end{bmatrix} \begin{bmatrix} p_0(s) \\ p_1(s) \\ \vdots \\ p_M(s) \end{bmatrix}$$

S.Pozza, N. Van Buggenhout

Function of interest

$$f(t,s) = \tilde{f}(t)\Theta(t-s)$$

Use Legendre polynomials $\{p_k\}_{k=0}^{M}$

$$\int_{-1}^{1} p_k(\tau) p_l(\tau) d\tau = \begin{cases} 0, & \text{if } k \neq l \\ 1, & \text{if } k = l \end{cases}$$

Legendre series

$$f(t,s) \approx \sum_{i=0}^{M} \sum_{j=0}^{M} f_{i,j} p_i(t) p_j(s) =: f_M(t,s)$$

$$f_M(t,s) = \begin{bmatrix} p_0(t) & p_1(t) & \dots & p_M(t) \end{bmatrix} F_M \begin{bmatrix} p_0(s) \\ p_1(s) \\ \vdots \\ p_M(s) \end{bmatrix}$$

The matrix algebra

In Legendre basis:

$$f(t,s) \approx \begin{bmatrix} p_0(t) & p_1(t) & \dots & p_M(t) \end{bmatrix} F_M \begin{bmatrix} p_0(s) \\ p_1(s) \\ \vdots \\ p_n(s) \end{bmatrix}$$

The matrix algebra

In Legendre basis:

$$f(t,s) \approx \begin{bmatrix} p_0(t) & p_1(t) & \dots & p_M(t) \end{bmatrix} F_M \begin{bmatrix} p_0(s) \\ p_1(s) \\ \vdots \\ p_n(s) \end{bmatrix}$$

$$\begin{array}{ll} f(t,s) & \qquad & F_{M} \\ \text{*-operation} & \qquad & \text{matrix operation} \\ s(t,s) = f(t,s) \star g(t,s) & \qquad & S_{M} = F_{M}G_{M} \\ f+g & \qquad & F_{M} + G_{M} \\ 1_{\star} = \delta(t-s) & \qquad & I_{M}, \text{ identity matrix} \\ f^{\star-1}(t,s) & \qquad & F_{M}^{-1} \\ R_{\star}(f)(t,s) := (1_{\star} - f)^{\star-1}(t,s) & \qquad & R(F_{M}) := (I_{M} - F_{M})^{-1} \end{array}$$

Solution to *-ODE:

$$\begin{array}{c} U(t,s) \\ \Theta(t-s) \star (1_{\star}-f)^{\star-1}(t,s) \end{array} \middle| \begin{array}{c} U_M \\ H_M (I_M - F_M)^{-1} \end{array}$$

Legendre approximation



Legendre approximation



S.Pozza, N. Van Buggenhout

Legendre approximation



Reconstruction and Gibbs phenomenon

Even if $\tilde{f}(t)$ is analytic, $f(t,s)=\tilde{f}(t)\Theta(t-s)$ is discontinuos. Therefore, the expansion

$$f(t,s) = \tilde{f}(t)\Theta(t-s) \approx \sum_{k=0}^{m-1} \sum_{\ell=0}^{m-1} \alpha_{k,\ell} p_k(t) p_\ell(s),$$

is affected by the so-called Gibbs phenomenon. Assuming to only know a matrix F, we may not be able to accurately reconstruct f(t, s).

Gibbs phenomenon

Gibbs phenomenon:

- Overshoot near discontinuity
- Spurious oscillations in whole domain



Is it really a problem?

For s = -1 the function $f(t, -1) = \tilde{f}(t)$, for $t \in [-1, 1]$. Therefore,

$$\tilde{f}(t) \approx f(t, -1) = \begin{bmatrix} p_0(t) & p_1(t) & \dots & p_M(t) \end{bmatrix} F_M \begin{bmatrix} p_0(-1) \\ p_1(-1) \\ \vdots \\ p_M(-1) \end{bmatrix}$$

Therefore $F_M \begin{bmatrix} p_0(-1) & p_1(-1) & \dots & p_M(-1) \end{bmatrix}^T$ is a vector containing the Legendre coefficients of the 1D expansion

$$\widetilde{f}(t) = \sum_{k=0}^{m-1} \widetilde{\alpha}_k p_k(t).$$

However, we still need to analyze the truncation error.

Solution

 $u(t,s) = \sum_{i=0}^{\infty} \sum_{j=0}^{\infty} u_{i,j} p_i(t) p_j(s) \approx \sum_{i=0}^{M} \sum_{j=0}^{M} u_{i,j} p_i(t) p_j(s)$



Solution

 $\tilde{u}(t) = u(t, -1) \approx \sum_{i=0}^{M} \sum_{j=0}^{M} u_{i,j} p_i(t) p_j(-1) = \sum_{i=0}^{M} \tilde{u}_i p_i(t)$



Solution

$$\tilde{u}(t) = u(t, -1) \approx \sum_{i=0}^{M} \sum_{j=0}^{M} u_{i,j} p_i(t) p_j(-1) = \sum_{i=0}^{M-b} \tilde{u}_i p_i(t)$$



Coefficient vector $ilde{u}$

Approximate solution



i

Coefficient vector $ilde{u}$

Approximate solution



Analytic solution: $u(t) = \exp\left(\frac{1}{4}\sin(4t)\right) = \sum_{i=0}^{\infty} \alpha_i p_i(t)$

Coefficient vector $ilde{u}$

Approximate solution



S.Pozza, N. Van Buggenhout

Proposed procedure

Solve $\frac{d}{dt}\tilde{u}(t) = \tilde{f}(t)\tilde{u}(t)$:

- 1. Represent $\tilde{f}(t)\Theta(t-s)$ as Legendre series $\Rightarrow F_M$
- 2. Compute $\tilde{\boldsymbol{u}}_M = H_M (I_M F_M)^{-1} p$ (GMRES!)
- 3. Choose right amount of coefficients to keep $ilde{u}_{M-b}$
- 4. Solution is $\tilde{u}(t) \approx \sum_{i=0}^{M-b} \tilde{u}_i p_i(t)$

Example

.

$$\frac{d}{dt}u(t) = \tilde{f}(t)u(t), \quad u(-1) = 1, \quad t \in [-1, 1]$$
$$\tilde{f}(t) = -2\pi i (0.1 + \cos(6\pi (t+1)) + \cos(12\pi (t+1)))$$



GMRES: 13 iterations for a 800×800 matrix.

S.Pozza, N. Van Buggenhout

Example



Left: Element magnitude of the Legendre coefficient matrix F. Right: Element magnitude of the computed Legendre coefficients c.

Proposed procedure

Compute $w^H \tilde{U}(t)v$, with $\frac{d}{dt}\tilde{U}(t) = \tilde{A}(t)\tilde{U}(t)$: 1. Represent $\tilde{A}(t)\Theta(t-s)$ as Legendre series $\Rightarrow \mathcal{F}_n$ block matrix $[F_{i,j}]_{i,j=1}^m$



- 2. Compute $w^H \tilde{U}_M v = (w \otimes I_M)^H \mathcal{H}_M (\mathcal{I}_M \mathcal{F}_M)^{-1} (v \otimes I_n) p$ (GMRES!)
- 3. Choose right amount of coefficients to keep $ilde{u}_{M-b}$
- 4. Solution is $w^H \tilde{U}(t) v \approx \sum_{i=0}^{M-b} \tilde{u}_i p_i(t)$

S.Pozza, N. Van Buggenhout

Kronecker structure

In many applications, the function $\tilde{A}(t)$ is given as a sum of Kronecker products:

$$\tilde{A}(t) = \sum_{j=0}^{s} A_j \otimes \tilde{f}_j(t),$$

with A_j sparse matrices, and $\tilde{f}_j(t)$ analytic functions. Our approach reformulates the problem as the linear system

$$(Id - \sum_{j=0}^{s} A_j \otimes F_j) \mathsf{vec}(X) = v \otimes \varphi_m(-1),$$

with F_j the Legendre discretization matrices, or, equivelently, as the matrix equation with a low-rank rhs

$$X - \sum_{j=0}^{s} F_j X A_j^T = \varphi_m(-1)v^T.$$

Experiment 1 [Baligács, Bonhomme]

Setup:

- $\ell=4~{\rm spins} \rightarrow 16\times 16$
- homonuclear dipolar coupling
- Magic angle spinning $\nu \in [5e3, 120e3]$
- $H(t) = D + B\cos(2\pi\nu t) + C\cos(4\pi\nu t)$
- time $t \in [0, 1e-4]$ (practical: $\mathcal{O}(e-2)$)
- Structure \boldsymbol{B} and \boldsymbol{C}

Compute:

- bilinear form $w^H \tilde{U}(t) v$
- Initial state $v = \begin{bmatrix} 1 & \dots & 1 \end{bmatrix}^\top \in \mathbb{C}^m$
- Measurement $w = \begin{bmatrix} 1 & \dots & 1 \end{bmatrix}^\top \in \mathbb{C}^m$

Experiment 1: numerical

Numerical:

-
$$\tilde{\boldsymbol{u}} := U_n p = H_n (I_n - F_n)^{-1} p \to \mathsf{GMRES}$$

- Reference solution \hat{u} : ode45 in Matlab

- Error: err :=
$$\|\hat{u}(t) - \sum_{i=0}^{n} \tilde{u}p_i(t)\|_{\infty}$$

Solution $\hat{u}(t)$



Result M = 300 & cutoff at k = 137



Quality of approximation M = 300, cutoff k = 137Coefficients:



For
$$\sum_{i=0}^{137} \tilde{u}_i p_i(t)$$
: err = 4.1 $e - 14$



S.Pozza, N. Van Buggenhout

Result M = 200 & cutoff at k = 137



Quality of approximation M = 200, cutoff k = 137Coefficients:



For
$$\sum_{i=0}^{137} \tilde{u}_i p_i(t)$$
: err = 4.7 $e - 14$



Quality of approximation M = 140, cutoff k = 100Coefficients:



For
$$\sum_{i=0}^{100} \tilde{u}_i p_i(t)$$
: err = 7.1 e - 9



Experiment 2 [Baligács, Bonhomme]

Setup:

- $\ell = 4~{\rm spins} \rightarrow 16 \times 16$
- uncoupled spins under a pulse wave
- $H(t) = A + B(0.5 + \cos(4t) + \sin(10t) 0.4\sin(16t)) + C(\sin(4t) + \cos(8t) + 2\sin(12t))$
- time $t \in [0, 1e{-}2]$
- Structure \boldsymbol{B} and \boldsymbol{C}

Solution $\hat{u}(t)$



Result M = 60 & cutoff at k = 44



Quality of approximation M = 60, cutoff k = 44Coefficients:



For
$$\sum_{i=0}^{44} \tilde{u}_i p_i(t)$$
: err = 4.4 e - 14



Recap

ODE: $\frac{d}{dt}U(t) = A(t)U(t)$

- New expression for U(t) = U(t, -1): $U(t, s) = \Theta(t - s) \star (1_{\star} - A(t)\Theta(t - s))^{\star - 1}$
- Legendre series: $ilde{m{u}} = U_M p$, with $U_M = H_M (I-F_M)^{-1}$
- Bandedness \Rightarrow recover decay of coefficients
- Efficient if:
 - fast solution linear system (Krylov + preconditioner!)
 - \circ good estimation of M

Recap

ODE: $\frac{d}{dt}U(t) = A(t)U(t)$

- New expression for U(t) = U(t, -1): $U(t, s) = \Theta(t - s) \star (1_{\star} - A(t)\Theta(t - s))^{\star - 1}$
- Legendre series: $ilde{m{u}} = U_M p$, with $U_M = H_M (I-F_M)^{-1}$
- Bandedness \Rightarrow recover decay of coefficients
- Efficient if:
 - fast solution linear system (Krylov + preconditioner!)
 - good estimation of ${\cal M}$

Future work

References

- S. P., N. V-B, paper in preparation
- P-L. Giscard, S. Pozza., Lanczos-like method for the time-ordered exponential, arXiv:1909.03437 [math.NA].
- P-L. Giscard, S. Pozza., Lanczos-like algorithm for the time-ordered exponential: The *-inverse problem, Applications of Mathematics, 2020.
- P-L. Giscard, S. Pozza, *Tridiagonalization of systems of coupled linear differential equations with variable coefficients by a Lanczos-like method*, Linear Algebra and its Applications, 2020.
- E. Baligács and C. Bonhomme, github.com/BaligacsEni/TOMEexamples.git, 2022.

Projects

- Charles University PRIMUS research poject: A Lanczos-like Method for the Time-Ordered Exponential, www.starlanczos.cz.
- French ANR research project: MAGICA (MAGnetic resonance techniques and Innovative Combinatorial Algebra).

Thank you for your attention!